Point processes for numerical integration

Diala Hawat

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- **1** Numerical integration and point processes
- 2 Repelled point processes
- 3 Diagnosing hyperuniform point processes
- 4 Conclusion and perspectives

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Numerical integration and point processes

Numerical integration and point processes

Let f be a continuous function supported on a compact $K \subset \mathbb{R}^d$.

Need: approximate $\int_{K} f(\mathbf{z}) \, \mathrm{d}\mathbf{z}$.

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For any $\{\mathbf{z}_i\}_{i=1}^N \subset K$ and $\{w_i\}_{i=1}^N \subset \mathbb{R}$, there exists $f \in \mathcal{F}^k$ s.t.

$$\left|\int_{\mathcal{K}} f(\mathbf{z}) \, \mathrm{d}\mathbf{z} - \sum_{i=1}^{N} w_i f(\mathbf{z}_i)\right| \geq \frac{C_1}{N^{k/d}}.$$



Fixed $\{\mathbf{z}_i\}_{i=1}^N$

N. Bakhvalov. Vestnik MGU, Ser. Math. Mech. Astron. Phys. Chem., 1959.

N. Bakhvalov. USSR Comp. Math. and Mathematical Physics, 1971.

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■ For $\{\mathbf{z}_i\}_{i=1}^N$ random elements of K and $\{w_i\}_{i=1}^N \subset \mathbb{R}$, there exists $f \in \mathcal{F}^k$ s.t.

Random $\{\mathbf{z}_i\}_{i=1}^N$

$$\mathbb{E}\Big[\Big|\int_{K}f(\mathbf{z})\,\mathrm{d}\mathbf{z}-\sum_{i=1}^{N}w_{i}f(\mathbf{z}_{i})\Big|\Big]\geq\frac{C_{2}}{N^{k/d+1/2}}$$

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Monte Carlo method

Numerical integration and point processes

Let \mathcal{X} be a stationary point process of intensity ρ

$$\int_{\mathcal{K}} f(\mathbf{z}) \, \mathrm{d}\mathbf{z} = \mathbb{E}\left[\sum_{\mathbf{z} \in \mathcal{X} \cap \mathcal{K}} \rho^{-1} f(\mathbf{z})\right].$$

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• Monte Carlo method:
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- Number of points: $\mathcal{X}(K)$ (random).
- $N := \mathbb{E}[\mathcal{X}(K)] = \rho|K|.$

 $\widehat{l}_{\mathcal{X}}(f) = \sum_{\mathbf{z} \in \mathcal{X} \cap K} \rho^{-1} f(\mathbf{z}) \approx \int_{K} f(\mathbf{z}) \, \mathrm{d}\mathbf{z}$

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Monte Carlo with a homogeneous Poisson point process (PPP):

Sampling from a PPP is fast.

•
$$Var[\hat{l}_{\mathcal{X}}(f)]^{1/2} = c(d, f)N^{-1/2}$$

A. B. Owen. Online book, 2013.

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Monte Carlo with a determinantal point process (DPP) :

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$$\operatorname{Var}[\widehat{l}_{\mathcal{X}}(f)]^{1/2} = O(N^{-1/2 - 1/(2d)}).$$

Sampling from DPPs is expensive.

R. Bardenet and A. Hardy. The Annals of Applied Probability, 2020.

J.-F. Coeurjolly, A. Mazoyer, and P.-O. Amblard. Electronic Journal of Statistics, 2021.

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G. Gautier, R. Bardenet, and M. Valko. Adv. in Neural Info. Processing Systems, 2019.

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Repelled point processes:

"D. Hawat, R. Bardenet, and R. Lachièze-Rey. Repelled point processes with application to numerical integration. Preprint, 2023."

1 Numerical integration and point processes

2 Repelled point processes

- Construction
- Theoretical results
- Experiments

3 Diagnosing hyperuniform point processes

4 Conclusion and perspectives

Repelled point processes Construction

 \mathcal{X} a stationary point process of intensity ρ of \mathbb{R}^d .



Sample

D. Hawat, R. Bardenet, and R. Lachièze-Rey. Preprint, 2023.

 \mathcal{X} a stationary point process of intensity ρ of \mathbb{R}^d .

Force:

$$F_{\mathcal{X}}(\mathbf{a}) := \sum_{\substack{\mathbf{z} \in \mathcal{X} \setminus \{\mathbf{a}\} \\ \|\mathbf{a} - \mathbf{z}\|_2 \uparrow}} \frac{\mathbf{a} - \mathbf{z}}{\|\mathbf{a} - \mathbf{z}\|_2^d}.$$



Sample

D. Hawat, R. Bardenet, and R. Lachièze-Rey. Preprint, 2023.

Chatterjee, Sourav, Ron Peled, Yuval Peres, and Dan Romik. Ann. of Mathematics, 2010.

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Repulsion operator:

$$\Pi_{\varepsilon}: \mathcal{X} \longmapsto \{\mathbf{a} + \varepsilon F_{\mathcal{X}}(\mathbf{a}) : \mathbf{a} \in \mathcal{X}\}.$$



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Repelled sample

D. Hawat, R. Bardenet, and R. Lachièze-Rey. Preprint, 2023.

Example



D. Hawat, R. Bardenet, and R. Lachièze-Rey. Preprint, 2023.

Main theoretical results

Repelled point processes Theoretical results

Let $\mathcal{P} \in \mathbb{R}^d$ be a PPP of intensity $\rho > 0$, $d \ge 3$, and $\varepsilon \in \mathbb{R}$.

• $\Pi_{\varepsilon}\mathcal{P}$ is a simple, stationary, isotropic point process of intensity ρ .

Proposition

For any two distinct points \mathbf{x} , \mathbf{y} of \mathbb{R}^d , the random vector $F_{\mathcal{P}}(\mathbf{x}) - F_{\mathcal{P}}(\mathbf{y})$ is continuous, i.e., for any $\mathbf{c} \in \mathbb{R}^d$,

$$\mathbb{P}\left(F_{\mathcal{P}}(\mathbf{x})-F_{\mathcal{P}}(\mathbf{y})=\mathbf{c}\right)=0.$$

Moreover, $\Pi_{\varepsilon} \mathcal{P}$ is a stationary and isotropic point process of intensity ρ .

D. Hawat, R. Bardenet, and R. Lachièze-Rey. Preprint, 2023.

Main theoretical results

Let $\mathcal{P} \in \mathbb{R}^d$ be a PPP of intensity $\rho > 0$, $d \ge 3$, and $\varepsilon \in \mathbb{R}$.

- **•** $\Pi_{\varepsilon}\mathcal{P}$ is a simple, stationary, isotropic point process of intensity ρ .
- For any $\varepsilon \in (-1, 1)$, the moments of $\Pi_{\varepsilon} \mathcal{P}$ exist.

Proposition

For any positive integer m and R > 0, we have

$$\mathbb{E}\left[\left(\sum_{\boldsymbol{z}\in \Pi_{\mathcal{E}}\mathcal{P}}\mathbbm{1}_{B(0,R)}(\boldsymbol{z})\right)^m\right]<\infty.$$

D. Hawat, R. Bardenet, and R. Lachièze-Rey. Preprint, 2023.

Proof's main idea: $\mathbb{E}[(\sum_{\mathbf{z}\in \Pi_{\varepsilon}\mathcal{P}} \mathbb{1}_{B(\mathbf{0},R)}(\mathbf{z}))^m] < \infty$

Repelled point processes Theoretical results

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•
$$F_{\mathcal{P}}(\mathbf{x}) = F_{\mathcal{P}}^{(0,1)}(\mathbf{x}) + F_{\mathcal{P}}^{(1,\infty)}(\mathbf{x}).$$



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Repelled point processes Theoretical results

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$$F_{\mathcal{P}}(\mathbf{x}) = F_{\mathcal{P}}^{(0,1)}(\mathbf{x}) + F_{\mathcal{P}}^{(1,\infty)}(\mathbf{x}).$$

$$For \mathbf{x} \in \mathcal{P} \cap B(\mathbf{0}, R)^{c}, \text{ if } \mathbf{x} + \varepsilon F_{\mathcal{P}}(\mathbf{x}) \in B(\mathbf{0}, R):$$

$$\mathbf{1} \quad \mathbf{x} + \varepsilon F_{\mathcal{P}}^{(0,1)}(\mathbf{x}) \in B(\mathbf{0}, r(\mathbf{x})).$$

$$\mathbf{2} \quad \|F_{\mathcal{P}}^{(1,\infty)}(\mathbf{x})\|_{2} \ge \frac{r(\mathbf{x}) - R}{|\varepsilon|}.$$





(2)

Main theoretical results

Let $\mathcal{P} \in \mathbb{R}^d$ be a PPP of intensity $\rho > 0$, $d \ge 3$, and $\varepsilon \in \mathbb{R}$.

- **•** $\Pi_{\varepsilon}\mathcal{P}$ is a simple, stationary, isotropic point process of intensity ρ .
- For any $\varepsilon \in (-1, 1)$, the moments of $\Pi_{\varepsilon} \mathcal{P}$ exist.
- For $\varepsilon > 0$ small enough and $f \in C^2(\mathbb{R}^d)$, $\mathbb{V}ar[\widehat{l}_{\Pi_{\varepsilon}\mathcal{P}}(f)] < \mathbb{V}ar[\widehat{l}_{\mathcal{P}}(f)]$.

Theorem

For any function $f \in C^2(\mathbb{R}^d)$ of compact support K, we have

$$\mathbb{V} \operatorname{ar} \left[\widehat{l}_{\Pi_{\varepsilon} \mathcal{P}}(f) \right] = \mathbb{V} \operatorname{ar} \left[\widehat{l}_{\mathcal{P}}(f) \right] (1 - 2d\kappa_d \rho \varepsilon) + O(\varepsilon^2),$$

where κ_d is the volume of the unit ball of \mathbb{R}^d .

D. Hawat, R. Bardenet, and R. Lachièze-Rey. Preprint, 2023.

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D. Hawat, R. Bardenet, and R. Lachièze-Rey. Preprint, 2023.

Repelled point processes Experiments

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Repelled point processes Experiments



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D. Hawat, R. Bardenet, and R. Lachièze-Rey. Preprint, 2023.

Diagnosing hyperuniformity:

"D. Hawat, G. Gautier, R. Bardenet, R. Lachièze-Rey. On estimating the structure factor of a point process, with applications to hyperuniformity. Statistics and Computing, 2023."

1 Numerical integration and point processes

2 Repelled point processes

- 3 Diagnosing hyperuniform point processes
 - Hyperuniformity
 - Hyperuniformity test

4 Conclusion and perspectives

Hyperuniformity

Diagnosing hyperuniform point processes Hyperuniformity

Let \mathcal{X} be a stationary point process of \mathbb{R}^d , \mathcal{X} is hyperuniform iff

$$\lim_{R \to \infty} \frac{\operatorname{Var}\left[\sum_{\mathbf{z} \in \mathcal{X}} \mathbbm{1}_{B(\mathbf{0},R)}(\mathbf{z})\right]}{|B(\mathbf{0},R)|} = 0.$$

S. Torquato. Hyperuniform States of Matter. Physics Reports, 2018.

S. Coste. Order, Fluctuations, Rigidities. Online survey, 2021.

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Hyperuniformity using the structure factor

Diagnosing hyperuniform point processes Hyperuniformity

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 ${\mathcal X}$ a stationary point process of intensity ρ

• Structure factor of $\mathcal X$

$$S(\mathbf{k}) = 1 + \rho \mathcal{F}(g-1)(\mathbf{k}).$$

\mathcal{X} is hyperuniform iff

 $S(\mathbf{0})=0.$

S. Torquato. Physics Reports, 2018.

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S. Coste. Online survey, 2021.

Diagnosing hyperuniform point processes Hyperuniformity test

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• **Given:** Realization of \mathcal{X} in a window W_L of lenghtside L (e.g., $W_L = [-L/2, L/2]^d$).

Diagnosing hyperuniform point processes Hyperuniformity test

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- Given: Realization of \mathcal{X} in a window W_L of lenghtside L (e.g., $W_L = [-L/2, L/2]^d$).
- **Estimator of** *S*:

$$\widehat{S}(\mathbf{k}) := \frac{1}{\rho |W_L|} \left| \sum_{z \in \mathcal{X} \cap W_L} e^{-i \langle \mathbf{k}, \mathbf{z} \rangle} \right|^2, \quad \mathbf{k} \in \mathbb{A}_L.$$

We have:

1
$$\|\mathbf{k}_{L}^{\min}\|_{2} := \min_{\mathbf{k} \in \mathbb{A}_{L}} \|\mathbf{k}\|_{2} = \frac{C}{L}.$$

2 For $\mathbf{k} \in \mathbb{A}_{L}$, $S(\mathbf{k}) = \lim_{W_{L} \uparrow \mathbb{R}^{d}} \mathbb{E}[\widehat{S}(\mathbf{k})].$

- S. Torquato. Physics Reports, 2018.
- M. A. Klatt et al. Nature Communications, 2019.
- M. A. Klatt, G. Last, and D. Yogeshwaran. Random Structures Algorithms, 2020.

Diagnosing hyperuniform point processes Hyperuniformity test

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M. A. Klatt, G. Last, and N. Henze. Preprint, 2022.

Diagnosing hyperuniform point processes Hyperuniformity test

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C. Rhee and P.W. Glynn. Operations Research, 2015.

Diagnosing hyperuniform point processes Hyperuniformity test

Let:

- 1 $\{W_{L_m}\}_{m\geq 1}$ an increasing sequence of windows s.t., $W_{L_{\infty}} = \mathbb{R}^d$.
- 2 \$\hinspace{S}_m\$ an estimator of \$\mathcal{S}\$ based on the points of \$\mathcal{X}\$ ∩ \$W_{L_m}\$.
 3 \$\mathbf{k}_{L_m}^{min}\$ a minimum allowed wavevector for the estimator \$\hinspace{S}_m\$.



Diagnosing hyperuniform point processes Hyperuniformity test

Let:

- {W_{L_m}}_{m≥1} an increasing sequence of windows s.t., W_{L∞} = ℝ^d.
 S_m an estimator of S based on the points of X ∩ W_{Lm}.
 - $2 \quad S_m$ an estimator of S based on the points of $\mathcal{X} + \mathcal{W}_{L_m}$.
- **3** $\mathbf{k}_{L_m}^{\min}$ a minimum allowed wavevector for the estimator \widehat{S}_m .

Define:

$$Z = \sum_{m=1}^{M} rac{Y_m - Y_{m-1}}{\mathbb{P}(M \ge m)}$$
 ,

with $Y_m = 1 \wedge \widehat{S}_m(\mathbf{k}_{L_m}^{\min})$, $Y_0 = 0$, and M an unbounded \mathbb{N} -r.v.

Diagnosing hyperuniform point processes Hyperuniformity test

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Proposition

Assume that $M \in L^p$ for some $p \ge 1$. Then $Z \in L^p$ and we have

- **1** If \mathcal{X} is hyperuniform, then $\mathbb{E}[Z] = 0$.
- 2 If \mathcal{X} is not hyperuniform and $\sup_{m} \mathbb{E}[\widehat{S}_{m}^{2}(\mathbf{k}_{L_{m}}^{\min})] < \infty$, then $\mathbb{E}[Z] \neq 0$.

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Assume that $M \in L^p$ for some $p \ge 1$. Then $Z := \sum_{j=1}^{M} \frac{Y_j - Y_{j-1}}{\mathbb{P}(M \ge j)} \in L^p$ and

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- 2 If \mathcal{X} is not hyperuniform and $\sup_m \mathbb{E}[\widehat{S}_m^2(\mathbf{k}_{L_m}^{\min})] < \infty$, then $\mathbb{E}[Z] \neq 0$.
- $Y_m = 1 \wedge \widehat{S}_m(\mathbf{k}_{L_m}^{\min}).$
- If \mathcal{X} is hyperuniform: $\mathbb{E}[Y_m] \xrightarrow[m \to \infty]{} S(\mathbf{0}) = 0.$
- If \mathcal{X} is not hyperuniform and $\sup_m \mathbb{E}[\widehat{S}_m^2(\mathbf{k}_{L_m}^{\min})] < \infty$: $\mathbb{E}[Y_m] \not\rightarrow 0$.

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- 2 If \mathcal{X} is not hyperuniform and $\sup_m \mathbb{E}[\widehat{S}_m^2(\mathbf{k}_{L_m}^{\min})] < \infty$, then $\mathbb{E}[Z] \neq 0$.
- $Y_m = 1 \land \widehat{S}_m(\mathbf{k}_{L_m}^{\min}).$ • If \mathcal{X} is hyperuniform: $\mathbb{E}[Y_m] \xrightarrow[m \to \infty]{} S(\mathbf{0}) = 0.$ • If \mathcal{X} is not hyperuniform and $\sup_m \mathbb{E}[\widehat{S}_m^2(\mathbf{k}_{L_m}^{\min})] < \infty$: $\mathbb{E}[Y_m] \xrightarrow[m \to \infty]{} \mathbb{E}[Z]$?

$$Z_m := \sum_{j=1}^{m \wedge M} \frac{Y_j - Y_{j-1}}{\mathbb{P}(M \ge j)}$$

Proposition

Assume that $M \in L^p$ for some $p \ge 1$. Then $Z := \sum_{j=1}^{M} \frac{Y_j - Y_{j-1}}{\mathbb{P}(M \ge j)} \in L^p$ and

- **1** If \mathcal{X} is hyperuniform, then $\mathbb{E}[Z] = 0$.
- 2 If \mathcal{X} is not hyperuniform and $\sup_m \mathbb{E}[\widehat{S}_m^2(\mathbf{k}_{L_m}^{\min})] < \infty$, then $\mathbb{E}[Z] \neq 0$.
- $Y_m = 1 \land \widehat{S}_m(\mathbf{k}_{L_m}^{\min}).$ • If \mathcal{X} is hyperuniform: $\mathbb{E}[Y_m] \xrightarrow[m \to \infty]{} S(\mathbf{0}) = 0.$ • If \mathcal{X} is not hyperuniform and $\sup_m \mathbb{E}[\widehat{S}_m^2(\mathbf{k}_{L_m}^{\min})] < \infty$: $\mathbb{E}[Y_m] \not\rightarrow 0.$ • $\mathbb{E}[Y_m] \xrightarrow[m \to \infty]{} \mathbb{E}[Z]$? • $Z_m := \sum_{i=1}^{m \land M} \frac{Y_j - Y_{j-1}}{\mathbb{P}(M > i)}$ and $\mathbb{E}[Z_m] = \mathbb{E}[Y_m].$

Proposition

Assume that $M \in L^p$ for some $p \ge 1$. Then $Z := \sum_{j=1}^{M} \frac{Y_j - Y_{j-1}}{\mathbb{P}(M \ge j)} \in L^p$ and

- **1** If \mathcal{X} is hyperuniform, then $\mathbb{E}[Z] = 0$.
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• $Z_m := \sum_{j=1}^{m \wedge M} \frac{Y_j - Y_{j-1}}{\mathbb{P}(M \ge j)} \xrightarrow[m \to \infty]{\text{a.s.}} Z$ and $\mathbb{E}[Z_m] = \mathbb{E}[Y_m].$

Diagnosing hyperuniform point processes Hyperuniformity test

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Proposition

Assume that $M \in L^p$ for some $p \ge 1$. Then $Z := \sum_{j=1}^{M} \frac{Y_j - Y_{j-1}}{\mathbb{P}(M \ge j)} \in L^p$ and

- 1 If \mathcal{X} is hyperuniform, then $\mathbb{E}[Z] = 0$.
- 2 If \mathcal{X} is not hyperuniform and $\sup_m \mathbb{E}[\widehat{S}_m^2(\mathbf{k}_{L_m}^{\min})] < \infty$, then $\mathbb{E}[Z] \neq 0$.
- i.i.d. pairs $(\mathcal{X}_a, M_a)_{a=1}^A$ of realizations of (\mathcal{X}, M) .

Asymptotic confidence interval of level ζ

$$CI[\mathbb{E}[Z]] = \left[\overline{Z}_A - z\overline{\sigma}_A A^{-1/2}, \overline{Z}_A + z\overline{\sigma}_A A^{-1/2}\right],$$

with $\mathbb{P}(-z < \mathcal{N}(0, 1) < z) = \zeta$.

• Assessing whether 0 lies in $CI[\mathbb{E}[Z]]$.

Diagnosing hyperuniform point processes Hyperuniformity test

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S(**0**) = 0

S(0) = 0.1

S(**0**) = 0.5

S(**0**) = 0.9

	ĪΖΑ	$CI[\mathbb{E}[Z]]$
Ginibre, $S(0) = 0$	0.0057	[-0.0042, 0.0156]
Thinning $p = 0.9, \ S(0) = 0.1$	0.0865	[0.0411, 0.1318]
Thinning $p = 0.5$, $S(0) = 0.5$	0.5722	[0.4227, 0.7217]
Thinning $p = 0.1$, $S(0) = 0.9$	0.611	[0.2082, 1.0137]

Table: Multiscale hyperuniformity test



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- Open-source Python toolbox called structure-factor.
- 2 Available on **Q** GitHub and PyPI.
- 3 Detailed documentation.
- 4 Jupyter notebook tutorial.



♥ structure-factor

https://github.com/For-a-few-DPPs-more/structure-factor https://pypi.org/project/structure-factor/

Conclusion and perspectives

Repelled point processes

- Conclusion:
 - **1** Introduced the repulsion operator.
 - 2 Proved variance reduction of repelled PPPs.
- Perspectives:
 - **1** Prove variance reduction for stationary point processes.
 - **2** Generalize to non-homogeneous PPPs.

D. Hawat, R. Bardenet, and R. Lachieze-Rey. Python package MCRPPy. GitHub, 2023.

D. Hawat, R. Bardenet, and R. Lachièze-Rey. Repelled point processes with application to numerical integration. *Preprint*, 2023.

Conclusion and perspectives

Diagnosing hyperuniform point processes

- Conclusion:
 - 1 Proposed a statistical test of hyperuniformity.
 - 2 Provided a Python toolbox structure-factor.
- Perspectives:
 - **1** Investigate the test for $S(\mathbf{0}) < 0.1$.
 - 2 Explore the possibility of employing in the test a single realization of the point process of moderate size.

D. Hawat, G. Gautier, R. Bardenet, and R. Lachièze-Rey. On estimating the structure factor of a point process, with applications to hyperuniformity. *Statistics and Computing*, 2023.

D. Hawat, G. Gautier, R. Bardenet, and R. Lachieze-Rey. Python package structure-factor. *GitHub and PyPI*, 2022.



Papers:

- **1 D. Hawat**, R. Bardenet, and R. Lachieze-Rey. Repelled point processes with application to numerical integration, *Preprint, Axiv, HAL*, 2023.
- **2 D. Hawat**, G. Gautier, R. Bardenet, and R. Lachièze-Rey. On estimating the structure factor of a point process, with applications to hyperuniformity. *Statistics and Computing*, 2023.
- **3 D. Hawat**, G. Gautier, R. Bardenet, and R. Lachieze-Rey. Estimation de la fonction de structure d'un processus ponctuel pour l'étude d'hyperuniformité. *GRETSI*, 2022.

Softwares:

- **D. Hawat**, R. Bardenet, and R. Lachieze-Rey. Python package MCRPPy. *GitHub*, 2023.
- **2 D. Hawat**, G. Gautier, R. Bardenet, and R. Lachieze-Rey. Python package structure-factor. *GitHub and PyPI*, 2022.

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Hyperuniformity class

2 \mathcal{X} is hyperuniform with $|S(\mathbf{k})| \sim c \|\mathbf{k}\|_2^{\alpha}$ in the neighborhood of 0 then

α	\mathbb{V} ar $\left[\sum_{\mathbf{z}\in\mathcal{X}}\mathbb{1}_{B(0,R)}(\mathbf{z}) ight]$	Class
> 1	$O(R^{d-1})$	Ι
1	$O(R^{d-1}\log(R))$	
]0,1[$O(R^{d-lpha})$	

By appropriately rescaling \mathcal{X} , we get an unbiased Monte Carlo method $\hat{l}_{\mathcal{X}}$ s.t. for f an indicator function we have

Class	\mathbb{V} ar $[\widehat{l}_{\mathcal{X}}(f)]^{1/2}$
1	$O(N^{-1/2-1/(2d)})$
П	$O(N^{-1/2-1/(2d)}\log(N))$
	$O(N^{-1/2-lpha/(2d)})$

- S. Coste. Order, Fluctuations, Rigidities. Online survey, 2021.
- S. Torquato. Hyperuniform States of Matter. Physics Reports, 2018.
- D. Hawat. Point processes for numerical integration. Ph.D. thesis, 2023.

Estimating the structure factor

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Given a realization of \mathcal{X} in $W = [-L/2, L/2]^d$:

• Estimator of *S*:

$$\widehat{S}_{\mathrm{SI,s}}(\mathbf{k}) \triangleq rac{1}{\mathcal{X}(W)} \left| \sum_{z \in \mathcal{X} \cap W} e^{-i \langle \mathbf{k}, \mathbf{z}
angle} \right|^2, \quad \mathbf{k} \in \mathbb{A}_L^{res}.$$

Allowed wavevectors:

$$\mathbb{A}_{L}^{res} = \left\{ \mathbf{k} = \left(\frac{2\pi n_1}{L}, \dots, \frac{2\pi n_d}{L}\right) \text{ with, } \mathbf{n} = (n_1, \dots, n_d) \in \mathbb{Z}^d \setminus \{\mathbf{0}\} \right\}$$

S. Torquato. Hyperuniform States of Matter. Physics Reports, 2018.

M. A. Klatt et al. Universal hidden order in amorphous cellular geometries. *Nature Communications*, 2019.

M. A. Klatt, G. Last, and D. Yogeshwaran. Hyperuniform and rigid stable matchings. *Random Structures Algorithms*, 2020.

M. A. Klatt, G. Last, and N. Henze. A genuine test for hyperuniformity. Preprint, 2022.

Estimating the structure factor

Thesis defense 27/11/2023

$$S(\mathbf{k}) = 1 + \rho \mathcal{F}(g-1)(\mathbf{k})$$

Given: A realization of a stationary point process \mathcal{X} of intensity ρ in $W = [-L/2, L/2]^d$.

• Need: Approximate $S(\mathbf{k}) = 1 + \rho \int_{\mathbb{R}^d} (g(\mathbf{r}) - 1) e^{-i \langle \mathbf{k}, \mathbf{r} \rangle} \, \mathrm{d}\mathbf{r}$.

$$S(\mathbf{k}) = 1 + \rho \int_{\mathbb{R}^d} \lim_{L \to \infty} (g(\mathbf{r}) - 1) \alpha_t(\mathbf{r}, W) e^{-i\langle \mathbf{k}, \mathbf{r} \rangle} \, \mathrm{d}\mathbf{r}$$
$$= \lim_{L \to \infty} \mathbb{E}[\widehat{S}(t, \mathbf{k})] - \underbrace{\rho \mathcal{F}(\alpha_t)(\mathbf{k}, W)}_{\epsilon_t(\mathbf{k}, \mathbf{L})}$$

with $\alpha_t(\mathbf{r}, W) = \int_{\mathbb{R}^d} t(\mathbf{r} + \mathbf{y}, W) t(\mathbf{y}, W) d\mathbf{y}$ s.t. $\lim_{L \to \infty} \alpha_t(\mathbf{r}, W) = 1$ and $\|t\|_2 = 1$.

D. Hawat, G. Gautier, R. Bardenet, R. Lachièze-Rey. On estimating the structure factor of a point process, with applications to hyperuniformity. *Statistics and Computing*, 2023.

Estimating the structure factor

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$$S(\mathbf{k}) = \lim_{L \to \infty} \mathbb{E} \left[\underbrace{\frac{1}{\rho |W|}}_{\widehat{S}_{SI}(\mathbf{k})} | \underbrace{\sum_{\mathbf{z} \in \mathcal{X} \cap W} e^{-i\langle \mathbf{k}, \mathbf{z} \rangle}}_{\widehat{S}_{SI}(\mathbf{k})} \right]^{2} - \rho \left(\underbrace{\prod_{j=1}^{d} \frac{\sin(k_{j}L/2)}{k_{j}\sqrt{L}/2}}_{\epsilon_{0}(\mathbf{k}, \mathbf{L})} \right)^{2}.$$

$$\bullet_{0}(\mathbf{k}, \mathbf{L}) = \begin{cases} 0 & \text{if } \mathbf{k} \in \mathbb{A}_{\mathbf{L}} \\ \rho L^{d} & \text{as } \|\mathbf{k}\|_{2} \to 0 \\ 2^{2d} \prod_{j=1}^{d} \frac{1}{Lk_{j}^{2}} & \text{as } \|\mathbf{k}\|_{2} \to \infty \end{cases}$$

$$\bullet_{\mathbf{L}} = \{(k_{1}, \dots, k_{d}) \in (\mathbb{R}^{d})^{*}, \exists j \in \{1, \dots, d\}, n \in \mathbb{Z}^{*} \text{ s.t. } k_{j} = \frac{2\pi n}{L}\}.$$

D. Hawat, G. Gautier, R. Bardenet, R. Lachièze-Rey. On estimating the structure factor of a point process, with applications to hyperuniformity. *Statistics and Computing*, 2023.

T. Rajala, S. Olhede, J. Grainger, and D. Murrell. What is the Fourier transform of a spatial point process? *IEEE Transactions on Information Theory*, 2023.

Estimating the structure factor

Thesis defense 27/11/2023

Our finding:

1 Estimator of *S*:

$$\widehat{S}_{\mathrm{SI}}(\mathbf{k}) = rac{1}{\mathbb{E}[\mathcal{X}(\mathcal{W})]} \left| \sum_{\mathbf{z} \in \mathcal{X} \cap \mathcal{W}} e^{-i \langle \mathbf{k}, \mathbf{z}
angle}
ight|^2, \quad \mathbf{k} \in \mathbb{A}_{\mathsf{L}}.$$

2 $\mathbb{A}_{\mathbf{L}} = \{ (k_1, \ldots, k_d) \in (\mathbb{R}^d)^*, \exists j \in \{1, \ldots, d\}, n \in \mathbb{Z}^* \text{ s.t. } k_j = \frac{2\pi n}{L} \}.$

Formulation in the literature:

1 Estimator of *S*:

$$\widehat{S}_{\mathrm{SI},\mathrm{s}}(\mathbf{k}) \triangleq \frac{1}{\mathcal{X}(W)} \left| \sum_{z \in \mathcal{X} \cap W} e^{-i \langle \mathbf{k}, \mathbf{z} \rangle} \right|^2, \quad \mathbf{k} \in \mathbb{A}_{\mathbf{L}}^{res}.$$
$$\mathbb{A}_{\mathbf{L}}^{res} = \left\{ \left(\frac{2\pi n_1}{L}, \dots, \frac{2\pi n_d}{L} \right) \text{ with, } \mathbf{n} = (n_1, \dots, n_d) \in \mathbb{Z}^d \setminus \{\mathbf{0}\} \right\}.$$

D. Hawat, G. Gautier, R. Bardenet, R. Lachièze-Rey. On estimating the structure factor of a point process, with applications to hyperuniformity. *Statistics and Computing*, 2023.

2

Coupled sum estimator

Estimating the structure factor

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- Need: estimate $\mathbb{E}[Y] := \overline{Y}$.
- Able to generate a sequence of r.v. $(Y_m)_m$ s.t. $\overline{Y} = \lim_{m \to \infty} \mathbb{E}[Y_m]$.

C. Rhee and P.W. Glynn. Unbiased estimation with square root convergence for SDE models. *Operations Research*, 2015.

• Need: estimate $\mathbb{E}[Y] := \overline{Y}$.

Able to generate a sequence of r.v. $(Y_m)_m$ s.t. $\overline{Y} = \lim_{m \to \infty} \mathbb{E}[Y_m]$.

Consider an N-r.v. M s.t., $\mathbb{P}(M \ge j) > 0$ for all j, and let $Y_0 = 0$

$$Z_m = \sum_{j=1}^{m \wedge M} \frac{Y_j - Y_{j-1}}{\mathbb{P}(M \ge j)}, \quad m \ge 1.$$

C. Rhee and P.W. Glynn. Unbiased estimation with square root convergence for SDE models. *Operations Research*, 2015.

• Need: estimate $\mathbb{E}[Y] := \overline{Y}$.

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- Consider an N-r.v. M s.t., $\mathbb{P}(M \ge j) > 0$ for all j, and let $Y_0 = 0$

$$Z_m = \sum_{j=1}^{m \wedge M} \frac{Y_j - Y_{j-1}}{\mathbb{P}(M \ge j)}, \quad m \ge 1.$$

•
$$\mathbb{E}[Z_m] = \mathbb{E}[Y_m]$$
 and $Z_m \xrightarrow[m \to \infty]{a.s.} Z := \sum_{j=1}^{M} \frac{Y_j - Y_{j-1}}{\mathbb{P}(M \ge j)}$.
• If $Y_m \xrightarrow[m \to \infty]{L^2} Y$ + some hypotheses, then $\mathbb{E}[Z] = \overline{Y}$.

C. Rhee and P.W. Glynn. Unbiased estimation with square root convergence for SDE models. *Operations Research*, 2015.

Estimating the structure factor

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