### Point processes for numerical integration

### Diala Hawat

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- **1** Numerical integration and point processes
- **2** Repelled point processes
- **3** Diagnosing hyperuniform point processes
- 4 Conclusion

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# Numerical integration and point processes

Numerical integration and point processes

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### Let f be a continuous fonction supported on a compact $K \subset \mathbb{R}^d$ .

Numerical integration and point processes

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• Approximation:  $\int_{\mathcal{K}} f(\mathbf{z}) d\mathbf{z} \approx \sum_{i=1}^{N} w_i f(\mathbf{z}_i)$ 



Numerical integration and point processes

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Fixed  $\{\mathbf{z}_i\}_{i=1}^N$ 

Diala Hawat

N. S. Bakhvalov. On the optimality of linear methods for operator approximation in convex classes of functions. *USSR Computational Mathematics and Mathematical Physics*, 1971.

E. Novak and H. Woźniakowski. Tractability of multivariate problems. Vol. 1: Linear information. *European Mathematical Society (EMS)*, 2008.

Let f be a continuous fonction supported on a compact  $K \subset \mathbb{R}^d$ .

- Approximation:  $\int_{K} f(\mathbf{z}) d\mathbf{z} \approx \sum_{i=1}^{N} w_i f(\mathbf{z}_i)$
- The worst-case error using fixed sets of N nodes is bounded from below by O(N<sup>-k/d</sup>).



Fixed  $\{\mathbf{z}_i\}_{i=1}^N$ 

N. S. Bakhvalov. On the approximate calculation of multiple integrals. *Vestnik MGU, Ser. Math. Mech. Astron. Phys. Chem.*, 1959.

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Random  $\{\mathbf{z}_i\}_{i=1}^N$ 

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Let f be a continuous fonction supported on a compact  $K \subset \mathbb{R}^d$ .

- Approximation:  $\int_{\mathcal{K}} f(\mathbf{z}) d\mathbf{z} \approx \sum_{i=1}^{N} w_i f(\mathbf{z}_i)$
- The worst-case error using fixed sets of N nodes is bounded from below by O(N<sup>-k/d</sup>).
- The worst-case RMSE using random sets of N nodes is bounded from below by  $O(N^{-k/d-1/2})$ .

```
Random \{\mathbf{z}_i\}_{i=1}^N
```

N. S. Bakhvalov. On the approximate calculation of multiple integrals. *Vestnik MGU, Ser. Math. Mech. Astron. Phys. Chem.*, 1959.

### **Monte Carlo method**

Numerical integration and point processes

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Let  $\mathcal X$  be a stationary point process of intensity  $\rho$ 

$$\mathbb{E}\left[\frac{1}{\rho}\sum_{\mathbf{z}\in\mathcal{X}\cap\mathcal{K}}f(\mathbf{z})\right] = \int_{\mathcal{K}}f(\mathbf{z})d\mathbf{z}.$$

Let  ${\mathcal X}$  be a stationary point process of intensity ho

$$\mathbb{E}\left[\underbrace{\frac{1}{\rho}\sum_{\mathbf{z}\in\mathcal{X}\cap\mathcal{K}}f(\mathbf{z})}_{:=\widehat{l}_{\mathcal{X}}(f)}\right] = \int_{\mathcal{K}}f(\mathbf{z})d\mathbf{z}.$$

• Monte Carlo method:  $\hat{l}_{\mathcal{X}}(f) = \frac{1}{\rho} \sum_{\mathbf{z} \in \mathcal{X} \cap \mathcal{K}} f(\mathbf{z}).$ 

• Number of points:  $\mathcal{X}(K)$  (random).

 $\bullet N := \mathbb{E}[\mathcal{X}(K)] = \rho|K|.$ 

 $\widehat{l}_{\mathcal{X}}(f) = \frac{1}{\rho} \sum_{\mathbf{z} \in \mathcal{X} \cap \mathcal{K}} f(\mathbf{z}) \approx \int_{\mathcal{K}} f(\mathbf{z}) d\mathbf{z}$ 

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 $\widehat{l}_{\mathcal{X}}(f) = \frac{1}{\rho} \sum_{\mathbf{z} \in \mathcal{X} \cap \mathcal{K}} f(\mathbf{z}) \approx \int_{\mathcal{K}} f(\mathbf{z}) d\mathbf{z}$ 

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Monte Carlo with a homogeneous Poisson point process (PPP):

Sampling from a PPP is fast.

• 
$$\operatorname{Var}[\widehat{I}_{\mathcal{X}}(f)]^{1/2} = c(d)N^{-1/2}$$



A. B. Owen. Monte Carlo theory, methods and examples. Online book, 2013.

 $\hat{l}_{\mathcal{X}}(f) = \frac{1}{\rho} \sum_{\mathbf{z} \in \mathcal{X} \cap K} f(\mathbf{z}) \approx \int_{K} f(\mathbf{z}) d\mathbf{z}$ 

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Monte Carlo with a determinantal point processes (DPP) :

• 
$$\operatorname{Var}[\widehat{l}_{\mathcal{X}}(f)]^{1/2} = O(N^{-1/2 - 1/(2d)})$$
.

■ Sampling from DPPs is expensive.

R. Bardenet and A. Hardy. Monte Carlo with determinantal point processes. *The Annals of Applied Probability*, 2020.

J.-F. Coeurjolly, A. Mazoyer, and P.-O. Amblard. Monte Carlo integration of non-differentiable functions on  $[0, 1]^i$ , i = 1, ..., d, using a single determinantal point pattern defined on  $[0, 1]^d$ . *Electronic Journal of Statistics*, 2021.

 $\widehat{l}_{\mathcal{X}}(f) = \frac{1}{\rho} \sum_{\mathbf{z} \in \mathcal{X} \cap K} f(\mathbf{z}) \approx \int_{K} f(\mathbf{z}) d\mathbf{z}$ 

#### Séminaire de Probabilités (MAP5) 10/11/2023



Monte Carlo with a determinantal point processes (DPP) :

• 
$$\operatorname{Var}[\widehat{l}_{\mathcal{X}}(f)]^{1/2} = O(N^{-1/2 - 1/(2d)})$$
.

■ Sampling from the DPP is expensive : at least O(N<sup>3</sup>).

R. Bardenet and A. Hardy. Monte Carlo with determinantal point processes. *The Annals of Applied Probability*, 2020.

G. Gautier, R. Bardenet, and M. Valko. On two ways to use determinantal point processes for Monte Carlo integration. *Advances in Neural Information Processing Systems*, 2019.

### Repelled point processes:

"D. Hawat, R. Bardenet, and R. Lachièze-Rey. Repelled point processes with application to numerical integration. Preprint, 2023."

### **1** Numerical integration and point processes

### 2 Repelled point processes

- Construction
- Theoretical results
- Experiments

#### **3** Diagnosing hyperuniform point processes

### 4 Conclusion

Repelled point processes Construction

 $\mathcal{X}$  a stationary point process of intensity  $\rho$  of  $\mathbb{R}^d$ .



Sample

D. Hawat, R. Bardenet, and R. Lachièze-Rey. Repelled point processes with application to numerical integration. *Preprint*, 2023.

Repelled point processes Construction

- $\mathcal X$  a stationary point process of intensity  $\rho$  of  $\mathbb R^d$ .
  - Force :

$$F_{\mathcal{X}}(\mathbf{a}) := \sum_{\substack{\mathbf{z} \in \mathcal{X} \setminus \{\mathbf{a}\} \\ \|\mathbf{a} - \mathbf{z}\|_2 \uparrow}} \frac{\mathbf{a} - \mathbf{z}}{\|\mathbf{a} - \mathbf{z}\|_2^d}.$$

Repulsion operator:

$$\Pi_{\varepsilon}: \mathcal{X} \longmapsto \{\mathbf{a} + \varepsilon F_{\mathcal{X}}(\mathbf{a}) : \mathbf{a} \in \mathcal{X}\}.$$



Sample

D. Hawat, R. Bardenet, and R. Lachièze-Rey. Repelled point processes with application to numerical integration. *Preprint*, 2023.

Chatterjee, Sourav, Ron Peled, Yuval Peres, and Dan Romik. Gravitational Allocation to Poisson Points. *Annals of Mathematics*, 2010.

 $\mathcal X$  a stationary point process of intensity  $\rho$  of  $\mathbb R^d$ .

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Repelled sample

D. Hawat, R. Bardenet, and R. Lachièze-Rey. Repelled point processes with application to numerical integration. *Preprint*, 2023.

### Example



D. Hawat, R. Bardenet, and R. Lachièze-Rey. Repelled point processes with application to numerical integration. *Preprint*, 2023.

Repelled point processes Theoretical results

Let  $\mathcal{P} \in \mathbb{R}^d$  be a PPP of intensity  $\rho > 0$ ,  $d \ge 3$ , and  $\varepsilon \in \mathbb{R}$ .

**I** $_{\varepsilon}\mathcal{P}$  is a simple, stationary and isotropic point process of intensity  $\rho$ .

Proposition

For any two distinct points  $\mathbf{x}$ ,  $\mathbf{y}$  of  $\mathbb{R}^d$ , the random vector  $F_{\mathcal{P}}(\mathbf{x}) - F_{\mathcal{P}}(\mathbf{y})$  is continuous, i.e., for any  $\mathbf{c} \in \mathbb{R}^d$ ,

$$\mathbb{P}\left(F_{\mathcal{P}}(\mathbf{x})-F_{\mathcal{P}}(\mathbf{y})=\mathbf{c}\right)=0.$$

Moreover,  $\Pi_{\varepsilon} \mathcal{P}$  is a stationary and isotropic point process of intensity  $\rho$ .

D. Hawat, R. Bardenet, and R. Lachièze-Rey. Repelled point processes with application to numerical integration. *Preprint*, 2023.

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- **I** $_{\varepsilon}\mathcal{P}$  is a simple, stationary and isotropic point process of intensity  $\rho$ .
- For any  $\varepsilon \in (-1, 1)$ : the moments of  $\Pi_{\varepsilon} \mathcal{P}$  exist.

Proposition

For any positive integer m and R > 0, we have

$$\mathbb{E}\left[\left(\sum_{\mathbf{z}\in \Pi_{arepsilon}\mathcal{P}}\mathbbm{1}_{B(0,R)}(\mathbf{z})
ight)^m
ight]<\infty.$$

D. Hawat, R. Bardenet, and R. Lachièze-Rey. Repelled point processes with application to numerical integration. *Preprint*, 2023.

### Main theoretical results

Repelled point processes Theoretical results

Let  $\mathcal{P} \in \mathbb{R}^d$  be a PPP of intensity  $\rho > 0$ ,  $d \ge 3$ , and  $\varepsilon \in \mathbb{R}$ .

- **•**  $\Pi_{\varepsilon}\mathcal{P}$  is a simple, stationary and isotropic point process of intensity  $\rho$ .
- For any  $\varepsilon \in (-1, 1)$  : the moments of  $\Pi_{\varepsilon} \mathcal{P}$  exist.
- For  $\varepsilon > 0$  small enough,  $f \in C^2(\mathbb{R}^d)$  :  $\mathbb{V}ar[\widehat{l}_{\Pi_{\varepsilon}\mathcal{P}}(f)]^{\frac{1}{2}} < \mathbb{V}ar[\widehat{l}_{\mathcal{P}}(f)]^{\frac{1}{2}}$ .

#### Theorem

For any function  $f \in C^2(\mathbb{R}^d)$  of compact support K, we have

$$\mathbb{V} \operatorname{ar} \left[ \widehat{I}_{\Pi_{\varepsilon} \mathcal{P}}(f) \right] = \mathbb{V} \operatorname{ar} \left[ \widehat{I}_{\mathcal{P}}(f) \right] (1 - 2d\kappa_d \rho \varepsilon) + O(\varepsilon^2),$$

where  $\kappa_d$  is the volume of the unit ball of  $\mathbb{R}^d$ .

D. Hawat, R. Bardenet, and R. Lachièze-Rey. Repelled point processes with application to numerical integration. *Preprint*, 2023.

### Main theoretical results

#### Repelled point processes Theoretical results

Let  $\mathcal{P} \in \mathbb{R}^d$  be a PPP of intensity  $\rho > 0$ ,  $d \ge 3$ , and  $\varepsilon \in \mathbb{R}$ .

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D. Hawat, R. Bardenet, and R. Lachièze-Rey. Repelled point processes with application to numerical integration. *Preprint*, 2023.

Repelled point processes Theoretical results

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- For any  $\varepsilon \in (-1, 1)$  : the moments of  $\Pi_{\varepsilon} \mathcal{P}$  exist.
- For  $\varepsilon > 0$  small enough,  $f \in C^2(\mathbb{R}^d)$  :  $\mathbb{V}ar[\widehat{l}_{\Pi_{\varepsilon}\mathcal{P}}(f)]^{\frac{1}{2}} < \mathbb{V}ar[\widehat{l}_{\mathcal{P}}(f)]^{\frac{1}{2}}$ .
- $\varepsilon_0 = 1/(2d\kappa_d \rho).$
- The computational complexity is O(N<sup>2</sup>) (parallalizable).

D. Hawat, R. Bardenet, and R. Lachièze-Rey. Repelled point processes with application to numerical integration. *Preprint*, 2023.

### Experiments 🛄

#### Repelled point processes Experiments

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D. Hawat, R. Bardenet, and R. Lachièze-Rey. Repelled point processes with application to numerical integration. *Preprint*, 2023.

### Experiments 🛄

Repelled point processes Experiments



D. Hawat, R. Bardenet, and R. Lachièze-Rey. Repelled point processes with application to numerical integration. *Preprint*, 2023.

### Experiments 🛄

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D. Hawat, R. Bardenet, and R. Lachièze-Rey. Repelled point processes with application to numerical integration. *Preprint*, 2023.

### Code availability

Repelled point processes Experiments

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- Open-source Python toolbox called MCRPPy.
- 2 Available on 🖓 GitHub.
- 3 Tutorial Jupyter notebook.



**O** MCRPPy

https://github.com/dhawat/MCRPPy/tree/main/notebooks

https://github.com/dhawat/MCRPPy

### Diagnosing hyperuniformity:

"D. Hawat, G. Gautier, R. Bardenet, R. Lachièze-Rey. On estimating the structure factor of a point process, with applications to hyperuniformity. Statistics and Computing, 2023."

### **1** Numerical integration and point processes

2 Repelled point processes

- 3 Diagnosing hyperuniform point processes
  - Hyperuniformity
  - Estimating the structure factor
  - Hyperuniformity test

Diagnosing hyperuniform point processes Hyperuniformity

Let X be a stationary point process of ℝ<sup>d</sup>, X is hyperuniform iff
Variance:

$$\lim_{R\to\infty}\frac{\operatorname{Var}\left[\sum_{\mathbf{z}\in\mathcal{X}}\mathbbm{1}_{B(0,R)}(\mathbf{z})\right]}{|B(0,R)|}=0.$$

S. Coste. Order, Fluctuations, Rigidities. Online survey, 2021.

S. Torquato. Hyperuniform States of Matter. Physics Reports, 2018.

Diagnosing hyperuniform point processes Hyperuniformity

Let  ${\mathcal X}$  be a stationary point process of  ${\mathbb R}^d,\,{\mathcal X}$  is hyperuniform iff

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S. Torquato. Hyperuniform States of Matter. Physics Reports, 2018.

Diagnosing hyperuniform point processes Hyperuniformity



Diagnosing hyperuniform point processes Hyperuniformity

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Diagnosing hyperuniform point processes Hyperuniformity

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Independent thinning of Ginibre



### Hyperuniformity using the structure factor

Diagnosing hyperuniform point processes Hyperuniformity

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$$\mathcal{X}$$
 is hyperuniform  $\iff \lim_{R \to \infty} \frac{\mathbb{V}ar[\sum_{\mathbf{z} \in \mathcal{X}} \mathbb{1}_{B(0,R)}(\mathbf{z})]}{|B(0,R)|} = 0$ 

Structure factor *S* of  $\mathcal{X}$  of intensity  $\rho$ 

$$S(\mathbf{k}) = 1 + \rho \mathcal{F}(g-1)(\mathbf{k}).$$

**\mathbf{\mathcal{X}}** is hyperuniform iff

 $S(\mathbf{0})=0.$ 

S. Coste. Order, Fluctuations, Rigidities. Online survey, 2021.

S. Torquato. Hyperuniform States of Matter. Physics Reports, 2018.

### Hyperuniformity class

Diagnosing hyperuniform point processes Hyperuniformity

•  $\mathcal{X}$  is hyperuniform with  $|S(\mathbf{k})| \sim c \|\mathbf{k}\|_2^{\alpha}$  in the neighborhood of 0 then

α	$\mathbb{V}$ ar $\left[\sum_{\mathbf{z}\in\mathcal{X}}\mathbb{1}_{B(0,R)}(\mathbf{z}) ight]$	Class
> 1	$O(R^{d-1})$	I
1	$O(R^{d-1}\log(R))$	11
]0, 1[	$O(R^{d-lpha})$	

S. Coste. Order, Fluctuations, Rigidities. Online survey, 2021.

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### Hyperuniformity class

Diagnosing hyperuniform point processes Hyperuniformity

**\mathcal{X}** is hyperuniform with  $|S(\mathbf{k})| \sim c \|\mathbf{k}\|_2^{\alpha}$  in the neighborhood of 0 then

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> 1	$O(R^{d-1})$	I
1	$O(R^{d-1}\log(R))$	II
]0,1[	$O(R^{d-lpha})$	

By appropriately rescaling  $\mathcal{X}$ , we get an unbiased Monte Carlo method  $\hat{l}_{\mathcal{X}}$  s.t. for f an indicator function we have

Class	$\mathbb{V}$ ar $[\widehat{l}_{\mathcal{X}}(f)]^{1/2}$
Ι	$O(N^{-1/2-1/(2d)})$
	$O(N^{-1/2-1/(2d)}\log(N))$
	$O(N^{-1/2-lpha/(2d)})$

D. Hawat. Point processes for numerical integration. Ph.D. thesis, 2023.

Estimating 
$$S(\mathbf{k}) = 1 + \rho \mathcal{F}(g-1)(\mathbf{k})$$

Diagnosing hyperuniform point processes Estimating the structure factor Séminaire de Probabilités (MAP5) 10/11/2023

Given a realization of  $\mathcal{X}$  in  $W = [-L/2, L/2]^d$ :

Estimator of S:

$$\widehat{\mathcal{S}}_{\mathrm{SI,s}}(\mathbf{k}) \triangleq rac{1}{\mathcal{X}(W)} \left| \sum_{z \in \mathcal{X} \cap W} e^{-i \langle \mathbf{k}, \mathbf{z} 
angle} \right|^2$$
,  $\mathbf{k} \in \mathbb{A}_L^{res}$ .

Allowed wavevectors:

$$\mathbb{A}_{L}^{res} = \left\{ \mathbf{k} = \left(\frac{2\pi n_{1}}{L}, \dots, \frac{2\pi n_{d}}{L}\right) \text{ with, } \mathbf{n} = (n_{1}, \dots, n_{d}) \in \mathbb{Z}^{d} \setminus \{\mathbf{0}\} \right\}$$

S. Torquato. Hyperuniform States of Matter. Physics Reports, 2018.

M. A. Klatt et al. Universal hidden order in amorphous cellular geometries. *Nature Communications*, 2019.

M. A. Klatt, G. Last, and D. Yogeshwaran. Hyperuniform and rigid stable matchings. *Random Structures Algorithms*, 2020.

M. A. Klatt, G. Last, and N. Henze. A genuine test for hyperuniformity. Preprint, 2022.

### Estimating $S(\mathbf{k}) = 1 + \rho \mathcal{F}(g-1)(\mathbf{k})$

Diagnosing hyperuniform point processes Estimating the structure factor Séminair

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• 
$$S(\mathbf{k}) = \lim_{L \to \infty} \mathbb{E}\left[\underbrace{\frac{1}{\rho|W|}}_{\mathbf{z} \in \mathcal{X} \cap W} e^{-i\langle \mathbf{k}, \mathbf{z} \rangle}\right]^{2} - \rho \underbrace{\left(\prod_{j=1}^{d} \frac{\sin(k_{j}L/2)}{k_{j}\sqrt{L}/2}\right)^{2}}_{\epsilon_{0}(\mathbf{k}, \mathbf{L})}$$
  
•  $\epsilon_{0}(\mathbf{k}, \mathbf{L}) = \begin{cases} 0 & \text{if } \mathbf{k} \in \mathbb{A}_{\mathbf{L}} \\ \rho L^{d} & \text{as } \|\mathbf{k}\|_{2} \to 0 \\ 2^{2d} \prod_{j=1}^{d} \frac{1}{Lk_{j}^{2}} & \text{as } \|\mathbf{k}\|_{2} \to \infty \end{cases}$   
•  $\mathbb{A}_{\mathbf{L}} = \{(k_{1}, \dots, k_{d}) \in (\mathbb{R}^{d})^{*}, \exists j \in \{1, \dots, d\}, n \in \mathbb{Z}^{*} \text{ s.t. } k_{j} = \frac{2\pi n}{L}\}.$ 

D. Hawat, G. Gautier, R. Bardenet, R. Lachièze-Rey. On estimating the structure factor of a point process, with applications to hyperuniformity. *Statistics and Computing*, 2023.

T. Rajala, S. Olhede, J. Grainger, and D. Murrell. What is the Fourier transform of a spatial point process? *IEEE Transactions on Information Theory*, 2023.

Diagnosing hyperuniform point processes Hyperuniformity test

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- Given: Realizations of  $\mathcal{X}$  in the window W of lenghtside L (e.g.,  $W = [-L/2, L/2]^d$ ).
- Need: Check if  $S(\mathbf{0}) = 0$ .
- Problem: We don't have an estimator of  $S(\mathbf{0})$ .
- We have:  $S(\mathbf{k}) = \lim_{L \to \infty} \mathbb{E} \left[ \widehat{S}(\mathbf{k}) \right]$  for  $\mathbf{k} \in \mathbb{A}_L$ , with  $\|\mathbf{k}_{min}\|_2 \sim \frac{C}{L}$ .

Diagnosing hyperuniform point processes Hyperuniformity test

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• Consider an increasing sequence of window  $\{W_m\}_m$  with  $W_{\infty} = \mathbb{R}^d$ .

• Let  $\mathbf{k}_m^{\min}$  the minimum wavevector in  $\mathbb{A}_{L_m}$ ,  $\mathbf{k}_m^{\min} \xrightarrow[m \to \infty]{} \mathbf{0}$ .



Diagnosing hyperuniform point processes Hyperuniformity test

Consider an increasing sequence of window {W<sub>m</sub>}<sub>m</sub> with W<sub>∞</sub> = ℝ<sup>d</sup>.
Let k<sup>min</sup><sub>m</sub> the minimum wavevector in A<sub>Lm</sub>, k<sup>min</sup><sub>m→∞</sub> 0.
Take
Z = ∑<sup>M</sup><sub>m=1</sub> Y<sub>m</sub> Y<sub>m-Ym-1</sub>/<sub>ℝ(M≥m)</sub>,

with  $Y_m = 1 \land \widehat{S}_m(\mathbf{k}_m^{\min})$  for  $m \ge 1$ ,  $Y_0 = 0$ , and M an unbounded  $\mathbb{N}$ -r.v.

C. Rhee and P.W. Glynn. Unbiased estimation with square root convergence for SDE models. *Operations Research*, 2015.

Diagnosing hyperuniform point processes Hyperuniformity test

Séminaire de Probabilités (MAP5) 10/11/2023

- Consider an increasing sequence of window  $\{W_m\}_m$  with  $W_{\infty} = \mathbb{R}^d$ .
- Let  $\mathbf{k}_m^{\min}$  the minimum wavevector in  $\mathbb{A}_{L_m}$ ,  $\mathbf{k}_m^{\min} \xrightarrow[m \to \infty]{} \mathbf{0}$ .
- Take

$$Z = \sum_{m=1}^{M} rac{Y_m - Y_{m-1}}{\mathbb{P}(M \ge m)}$$
 ,

with  $Y_m = 1 \land \widehat{S}_m(\mathbf{k}_m^{\min})$  for  $m \ge 1$ ,  $Y_0 = 0$ , and M an unbounded  $\mathbb{N}$ -r.v.

### Proposition

Assume that  $M \in L^p$  for some  $p \ge 1$ . Then  $Z \in L^p$  and we have,

- **1** If  $\mathcal{X}$  is hyperuniform, then  $\mathbb{E}[Z] = 0$ .
- 2 If  $\mathcal{X}$  is not hyperuniform and  $\sup_{m} \mathbb{E}[\widehat{S}_{m}^{2}(\mathbf{k}_{m}^{\min})] < \infty$ , then  $\mathbb{E}[Z] \neq 0$ .

D. Hawat, G. Gautier, R. Bardenet, R. Lachièze-Rey. On estimating the structure factor of a point process, with applications to hyperuniformity. *Statistics and Computing*, 2023.

Diagnosing hyperuniform point processes Hyperuniformity test

Need: Check if 
$$\mathbb{E}[Z] = 0$$
, with  $Z = \sum_{j=1}^{M} \frac{Y_j - Y_{j-1}}{\mathbb{P}(M \ge j)}$   
Test:

- *M* a Poisson r.v. of parameter  $\lambda$ .
- i.i.d. pairs  $(\mathcal{X}_a, M_a)_{a=1}^A$  of realizations of  $(\mathcal{X}, M)$ .
- Asymptotic confidence interval  $CI[\mathbb{E}[Z]]$  of level  $\zeta$ .

$$CI[\mathbb{E}[Z]] = \left[\bar{Z}_A - z\bar{\sigma}_A A^{-1/2}, \bar{Z}_A + z\bar{\sigma}_A A^{-1/2}\right]$$

with  $\mathbb{P}(-z < \mathcal{N}(0, 1) < z) = \zeta$ .

• Assessing whether 0 lies in  $CI[\mathbb{E}[Z]]$ .

Diagnosing hyperuniform point processes Hyperuniformity test



S(0) = 0

5(0)	= 0.1
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S(**0**) = 0.5

S(**0**) = 0.9

	ĪΖΑ	$CI[\mathbb{E}[Z]]$
Ginibre, $S(0) = 0$	0.0057	[-0.0042, 0.0156]
Thinning $p = 0.9$ , $S(0) = 0.1$	0.0865	[0.0411, 0.1318]
Thinning $p = 0.5$ , $S(0) = 0.5$	0.5722	[0.4227, 0.7217]
Thinning $p = 0.1, S(0) = 0.9$	0.611	[0.2082, 1.0137]

Table: Multiscale hyperuniformity test

### Code availability

Diagnosing hyperuniform point processes Hyperuniformity test

Séminaire de Probabilités (MAP5) 10/11/2023



- Open-source Python toolbox called structure-factor.
- Available on **O** GitHub and PyPI.
- 3 Detailed documentation.
- 4 Jupyter notebook tutorial.



♥ structure-factor

https://github.com/For-a-few-DPPs-more/structure-factor https://pypi.org/project/structure-factor/ https://for-a-few-dpps-more.github.io/structure-factor/ https://github.com/For-a-few-DPPs-more/structure-factor/tree/main/notebooks Conclusion

### Repelled point processes 1:

- Repulsion operator.
- Variance reduction of the repelled Poisson point process.
- Python toolbox MCRPPy.

Hyperuniform point processes <sup>2</sup> :

- Estimators of the structure factor.
- Statistical test of hyperuniformity.
- Python toolbox structure-factor.

<sup>&</sup>lt;sup>1</sup>D. Hawat, R. Bardenet, and R. Lachièze-Rey. Repelled point processes with application to numerical integration. *Preprint*, 2023.

<sup>&</sup>lt;sup>2</sup>D. Hawat, G. Gautier, R. Bardenet, and R. Lachièze-Rey. On estimating the structure factor of a point process, with applications to hyperuniformity. *Statistics and Computing*, 2023.

## THANK YOU !



Paper:

- **1** D. Hawat, R. Bardenet, and R. Lachieze-Rey. Repelled point processes with application to numerical integration, *Preprint, Axiv, HAL*, 2023.
- **2** D. Hawat, G. Gautier, R. Bardenet, and R. Lachièze-Rey. On estimating the structure factor of a point process, with applications to hyperuniformity. *Statistics and Computing*, 2023.
- 3 D. Hawat, G. Gautier, R. Bardenet, and R. Lachieze-Rey. Estimation de la fonction de structure d'un processus ponctuel pour l'étude d'hyperuniformité. XXVIIIème Colloque Francophone de Traitement du Signal et des Images GRETSI, 2022.

Software:

- **1** MCRPPy. Python package available on GitHub, 2023.
- 2 structure-factor. Python package available on GitHub and PyPI, 2022.