Point processes for numerical integration

Diala Hawat

Supervisors: Rémi Bardenet

and

Raphaël Lachièze-Rey

LPSM, Sorbonne Université.







- **1** Numerical integration and point processes
- 2 Repelled point processes
- **3** Diagnosing hyperuniform point processes
- 4 Conclusion and perspectives

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Numerical integration and point processes

Numerical integration and point processes

Let f be a continuous function supported on a compact $K \subset \mathbb{R}^d$.

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- Approximation: $\int_{\mathcal{K}} f(\mathbf{z}) \, \mathrm{d}\mathbf{z} \approx \sum_{i=1}^{N} w_i f(\mathbf{z}_i).$

For any $\{\mathbf{z}_i\}_{i=1}^N \subset K$ and $\{w_i\}_{i=1}^N \subset \mathbb{R}$, there exists $f \in \mathcal{F}^k$ s.t.

$$\left|\int_{\mathcal{K}} f(\mathbf{z}) \, \mathrm{d}\mathbf{z} - \sum_{i=1}^{N} w_i f(\mathbf{z}_i)\right| \geq \frac{C_1}{N^{k/d}}.$$



Fixed $\{\mathbf{z}_i\}_{i=1}^N$

N. Bakhvalov. Vestnik MGU, Ser. Math. Mech. Astron. Phys. Chem., 1959.

N. Bakhvalov. USSR Comp. Math. and Mathematical Physics, 1971.

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■ For $\{\mathbf{z}_i\}_{i=1}^N$ random elements of K and $\{w_i\}_{i=1}^N \subset \mathbb{R}$, there exists $f \in \mathcal{F}^k$ s.t.

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Random $\{\mathbf{z}_i\}_{i=1}^N$

$$\mathbb{E}\Big[\Big|\int_{\mathcal{K}}f(\mathbf{z})\,\mathrm{d}\mathbf{z}-\sum_{i=1}^{N}w_{i}f(\mathbf{z}_{i})\Big|\Big]\geq\frac{C_{2}}{N^{k/d+1/2}}.$$

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Monte Carlo method

Numerical integration and point processes

Let $\mathcal X$ be a stationary point process of intensity ho

$$\int_{\mathcal{K}} f(\mathbf{z}) \, \mathrm{d}\mathbf{z} = \mathbb{E}\left[\sum_{\mathbf{z} \in \mathcal{X} \cap \mathcal{K}} \rho^{-1} f(\mathbf{z})\right]$$

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• Monte Carlo method:
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$$\hat{l}_{\mathcal{X}}(f) = \sum_{\mathbf{z} \in \mathcal{X} \cap \mathcal{K}} \rho^{-1} f(\mathbf{z}).$$

- Number of points: $\mathcal{X}(K)$ (random).
- $N := \mathbb{E}[\mathcal{X}(K)] = \rho|K|.$

 $\widehat{l}_{\mathcal{X}}(f) = \sum_{\mathbf{z} \in \mathcal{X} \cap K} \rho^{-1} f(\mathbf{z}) \approx \int_{K} f(\mathbf{z}) \, \mathrm{d}\mathbf{z}$

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Monte Carlo with a homogeneous Poisson point process (PPP):

Sampling from a PPP is fast.

•
$$Var[\hat{l}_{\mathcal{X}}(f)]^{1/2} = c(d, f)N^{-1/2}$$

A. B. Owen. Online book, 2013.

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Monte Carlo with a determinantal point process (DPP) :

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$$\operatorname{Var}[\widehat{l}_{\mathcal{X}}(f)]^{1/2} = O(N^{-1/2 - 1/(2d)}).$$

Sampling from DPPs is expensive.

R. Bardenet and A. Hardy. The Annals of Applied Probability, 2020.

J.-F. Coeurjolly, A. Mazoyer, and P.-O. Amblard. Electronic Journal of Statistics, 2021.

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G. Gautier, R. Bardenet, and M. Valko. Adv. in Neural Info. Processing Systems, 2019.

Diala Hawat

Repelled point processes:

"D. Hawat, R. Bardenet, and R. Lachièze-Rey. Repelled point processes with application to numerical integration. Preprint, 2023."

1 Numerical integration and point processes

2 Repelled point processes

- Construction
- Theoretical results
- Experiments

3 Diagnosing hyperuniform point processes

4 Conclusion and perspectives

Repelled point processes Construction

 \mathcal{X} a stationary point process of intensity ρ of \mathbb{R}^d .



Sample

D. Hawat, R. Bardenet, and R. Lachièze-Rey. Preprint, 2023.

Repelled point processes Construction

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Force:

$$F_{\mathcal{X}}(\mathbf{a}) := \sum_{\substack{\mathbf{z} \in \mathcal{X} \setminus \{\mathbf{a}\} \\ \|\mathbf{a} - \mathbf{z}\|_2 \uparrow}} \frac{\mathbf{a} - \mathbf{z}}{\|\mathbf{a} - \mathbf{z}\|_2^d}.$$



Sample

D. Hawat, R. Bardenet, and R. Lachièze-Rey. Preprint, 2023.

Chatterjee, Sourav, Ron Peled, Yuval Peres, and Dan Romik. Ann. of Mathematics, 2010.

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Repulsion operator:

$$\Pi_{\varepsilon}: \mathcal{X} \longmapsto \{\mathbf{a} + \varepsilon F_{\mathcal{X}}(\mathbf{a}) : \mathbf{a} \in \mathcal{X}\}.$$



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Repelled sample

D. Hawat, R. Bardenet, and R. Lachièze-Rey. Preprint, 2023.

Example



D. Hawat, R. Bardenet, and R. Lachièze-Rey. Preprint, 2023.

Repelled point processes Theoretical results

Let $\mathcal{P} \in \mathbb{R}^d$ be a PPP of intensity $\rho > 0$, $d \ge 3$, and $\varepsilon \in \mathbb{R}$.

I $_{\varepsilon}\mathcal{P}$ is a simple, stationary, isotropic point process of intensity ρ .

Proposition

For any two distinct points \mathbf{x} , \mathbf{y} of \mathbb{R}^d , the random vector $F_{\mathcal{P}}(\mathbf{x}) - F_{\mathcal{P}}(\mathbf{y})$ is continuous, i.e., for any $\mathbf{c} \in \mathbb{R}^d$,

$$\mathbb{P}\left(F_{\mathcal{P}}(\mathbf{x})-F_{\mathcal{P}}(\mathbf{y})=\mathbf{c}\right)=0.$$

Moreover, $\Pi_{\varepsilon} \mathcal{P}$ is a stationary and isotropic point process of intensity ρ .

D. Hawat, R. Bardenet, and R. Lachièze-Rey. Preprint, 2023.

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- For any $\varepsilon \in (-1, 1)$, the moments of $\Pi_{\varepsilon} \mathcal{P}$ exist.

Proposition

For any positive integer m and R > 0, we have

$$\mathbb{E}\left[\left(\sum_{\boldsymbol{z}\in \Pi_{\varepsilon}\mathcal{P}}\mathbbm{1}_{B(\boldsymbol{0},R)}(\boldsymbol{z})\right)^{m}\right]<\infty.$$

D. Hawat, R. Bardenet, and R. Lachièze-Rey. Preprint, 2023.

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- **•** $\Pi_{\varepsilon}\mathcal{P}$ is a simple, stationary, isotropic point process of intensity ρ .
- For any $\varepsilon \in (-1, 1)$, the moments of $\Pi_{\varepsilon} \mathcal{P}$ exist.
- For $\varepsilon > 0$ small enough and $f \in C^2(\mathbb{R}^d)$, $\mathbb{V}ar[\widehat{l}_{\Pi_{\varepsilon}\mathcal{P}}(f)] < \mathbb{V}ar[\widehat{l}_{\mathcal{P}}(f)]$.

Theorem

For any function $f \in C^2(\mathbb{R}^d)$ of compact support K, we have

$$\mathbb{V} \operatorname{ar} \left[\widehat{l}_{\Pi_{\varepsilon} \mathcal{P}}(f) \right] = \mathbb{V} \operatorname{ar} \left[\widehat{l}_{\mathcal{P}}(f) \right] (1 - 2d\kappa_d \rho \varepsilon) + O(\varepsilon^2),$$

where κ_d is the volume of the unit ball of \mathbb{R}^d .

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Repelled point processes Experiments

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D. Hawat, R. Bardenet, and R. Lachièze-Rey. Preprint, 2023.

Diagnosing hyperuniformity:

"D. Hawat, G. Gautier, R. Bardenet, R. Lachièze-Rey. On estimating the structure factor of a point process, with applications to hyperuniformity. Statistics and Computing, 2023."

1 Numerical integration and point processes

2 Repelled point processes

- 3 Diagnosing hyperuniform point processes
 - Hyperuniformity
 - Hyperuniformity test

4 Conclusion and perspectives

Hyperuniformity

Diagnosing hyperuniform point processes Hyperuniformity

Let \mathcal{X} be a stationary point process of \mathbb{R}^d , \mathcal{X} is hyperuniform iff

$$\lim_{R \to \infty} \frac{\operatorname{Var}\left[\sum_{\mathbf{z} \in \mathcal{X}} \mathbb{1}_{B(\mathbf{0},R)}(\mathbf{z})\right]}{|B(\mathbf{0},R)|} = 0.$$

S. Torquato. Hyperuniform States of Matter. Physics Reports, 2018.

S. Coste. Order, Fluctuations, Rigidities. Online survey, 2021.

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Hyperuniformity using the structure factor

Diagnosing hyperuniform point processes Hyperuniformity

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 ${\cal X}$ a stationary point process of intensity ρ

Structure factor of \mathcal{X}

$$S(\mathbf{k}) = 1 + \rho \mathcal{F}(g-1)(\mathbf{k}).$$

\mathcal{X} is hyperuniform iff

 $S(\mathbf{0})=0.$

S. Coste. Online survey, 2021.

S. Torquato. Physics Reports, 2018.

Diagnosing hyperuniform point processes Hyperuniformity test

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• **Given:** Realization of \mathcal{X} in a window W_L of lenghtside L (e.g., $W_L = [-L/2, L/2]^d$).

Diagnosing hyperuniform point processes Hyperuniformity test

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- Given: Realization of \mathcal{X} in a window W_L of lenghtside L (e.g., $W_L = [-L/2, L/2]^d$).
- **Estimator of** *S*:

$$\widehat{S}(\mathbf{k}) := \frac{1}{\rho |W_L|} \left| \sum_{z \in \mathcal{X} \cap W_L} e^{-i \langle \mathbf{k}, \mathbf{z} \rangle} \right|^2, \quad \mathbf{k} \in \mathbb{A}_L.$$

We have:

1
$$\|\mathbf{k}_{L}^{\min}\|_{2} := \min_{\mathbf{k} \in \mathbb{A}_{L}} \|\mathbf{k}\|_{2} = \frac{C}{L}.$$

2 For $\mathbf{k} \in \mathbb{A}_{L}$, $S(\mathbf{k}) = \lim_{W_{L} \uparrow \mathbb{R}^{d}} \mathbb{E}[\widehat{S}(\mathbf{k})].$

- S. Torquato. Physics Reports, 2018.
- M. A. Klatt et al. Nature Communications, 2019.
- M. A. Klatt, G. Last, and D. Yogeshwaran. Random Structures Algorithms, 2020.

Diagnosing hyperuniform point processes Hyperuniformity test

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M. A. Klatt, G. Last, and N. Henze. Preprint, 2022.

Diagnosing hyperuniform point processes Hyperuniformity test

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C. Rhee and P.W. Glynn. Operations Research, 2015.

Diagnosing hyperuniform point processes Hyperuniformity test

Let:

- 1 $\{W_{L_m}\}_{m\geq 1}$ an increasing sequence of windows s.t., $W_{L_{\infty}} = \mathbb{R}^d$.
- 2 \$\hinspace{S}_m\$ an estimator of \$S\$ based on the points of \$\mathcal{X} ∩ \$W_{L_m}\$.
 3 \$\mathbf{k}_{L_m}^{min}\$ a minimum allowed wavevector for the estimator \$\hinspace{S}_m\$.



Diagnosing hyperuniform point processes Hyperuniformity test

Let:

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 S_m an estimator of S based on the points of X ∩ W_{Lm}.
 - 2 S_m an estimator of S based on the points of $\mathcal{X} + \mathcal{W}_{L_m}$.
- **3** $\mathbf{k}_{L_m}^{\min}$ a minimum allowed wavevector for the estimator \widehat{S}_m .

Define:

$$Z = \sum_{m=1}^{M} \frac{Y_m - Y_{m-1}}{\mathbb{P}(M \ge m)}$$
,

with $Y_m = 1 \wedge \widehat{S}_m(\mathbf{k}_{L_m}^{\min})$, $Y_0 = 0$, and M an unbounded \mathbb{N} -r.v.

D. Hawat, G. Gautier, R. Bardenet, R. Lachièze-Rey. Statistics and Computing, 2023.

Diagnosing hyperuniform point processes Hyperuniformity test

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Proposition

Assume that $M \in L^p$ for some $p \ge 1$. Then $Z \in L^p$ and we have

- **1** If \mathcal{X} is hyperuniform, then $\mathbb{E}[Z] = 0$.
- 2 If \mathcal{X} is not hyperuniform and $\sup_{m} \mathbb{E}[\widehat{S}_{m}^{2}(\mathbf{k}_{L_{m}}^{\min})] < \infty$, then $\mathbb{E}[Z] \neq 0$.

D. Hawat, G. Gautier, R. Bardenet, R. Lachièze-Rey. Statistics and Computing, 2023.

Diagnosing hyperuniform point processes Hyperuniformity test

Proposition

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- **1** If \mathcal{X} is hyperuniform, then $\mathbb{E}[Z] = 0$.
- 2 If \mathcal{X} is not hyperuniform and $\sup_m \mathbb{E}[\widehat{S}_m^2(\mathbf{k}_{L_m}^{\min})] < \infty$, then $\mathbb{E}[Z] \neq 0$.
- i.i.d. pairs $(\mathcal{X}_a, M_a)_{a=1}^A$ of realizations of (\mathcal{X}, M) .

Asymptotic confidence interval of level ζ

$$CI[\mathbb{E}[Z]] = \left[\overline{Z}_A - z\overline{\sigma}_A A^{-1/2}, \overline{Z}_A + z\overline{\sigma}_A A^{-1/2}\right],$$

with $\mathbb{P}(-z < \mathcal{N}(0, 1) < z) = \zeta$.

• Assessing whether 0 lies in $CI[\mathbb{E}[Z]]$.

Diagnosing hyperuniform point processes Hyperuniformity test



S(**0**) = 0

SI	(0)	=	0	.1
-	- /			

S(**0**) = 0.5

S(**0**) = 0.9

	ĪΖΑ	$CI[\mathbb{E}[Z]]$
Ginibre, $S(0) = 0$	0.0057	[-0.0042, 0.0156]
Thinning $p = 0.9, S(0) = 0.1$	0.0865	[0.0411, 0.1318]
Thinning $p = 0.5$, $S(0) = 0.5$	0.5722	[0.4227, 0.7217]
Thinning $p = 0.1, S(0) = 0.9$	0.611	[0.2082, 1.0137]

Table: Multiscale hyperuniformity test



Diagnosing hyperuniform point processes Hyperuniformity test

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- Open-source Python toolbox called structure-factor.
- 2 Available on **Q** GitHub and PyPI.
- 3 Detailed documentation.
- 4 Jupyter notebook tutorial.



O structure-factor

https://github.com/For-a-few-DPPs-more/structure-factor https://pypi.org/project/structure-factor/

Conclusion and perspectives

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Repelled point processes



Conclusion and perspectives

Conclusion and perspectives

Diagnosing hyperuniform point processes





Papers:

- **1** D. Hawat, R. Bardenet, and R. Lachieze-Rey. Repelled point processes with application to numerical integration, *Preprint, Axiv, HAL*, 2023.
- **2** D. Hawat, G. Gautier, R. Bardenet, and R. Lachièze-Rey. On estimating the structure factor of a point process, with applications to hyperuniformity. *Statistics and Computing*, 2023.

Softwares:

- **1** D. Hawat, R. Bardenet, and R. Lachieze-Rey. Python package MCRPPy. *GitHub*, 2023.
- **2** D. Hawat, G. Gautier, R. Bardenet, and R. Lachieze-Rey. Python package structure-factor. *GitHub and PyPI*, 2022.